

Signals and Systems

Introduction 80

- * Signal :- is a function of independent variables such as time, frequency, position.
- * System :- is an interconnection of components with terminals that allow the exchange of energy, matters or information.
- * Signal Processing :- is concerned with the mathematical representation of the signal and the algorithmic operation carried out on it to extract the information present.

Discrete time signals 80

Discrete time signals are often derived by sampling a continuous time signal such as speech with an analog to digital converter (A/D)

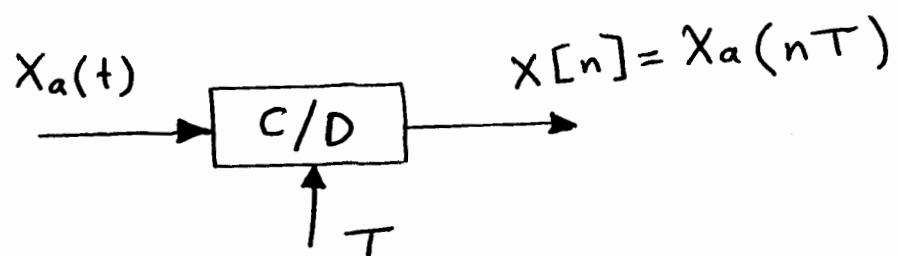
* the typical method of obtaining a discrete-time representation of a continuous-time signal is through Period sampling

$$X[n] = X_a(nT) \quad -\infty < n < \infty$$

where T is called the sampling period its reciprocal $f_s = \frac{1}{T}$ is the sampling frequency

we also express the sampling frequency as

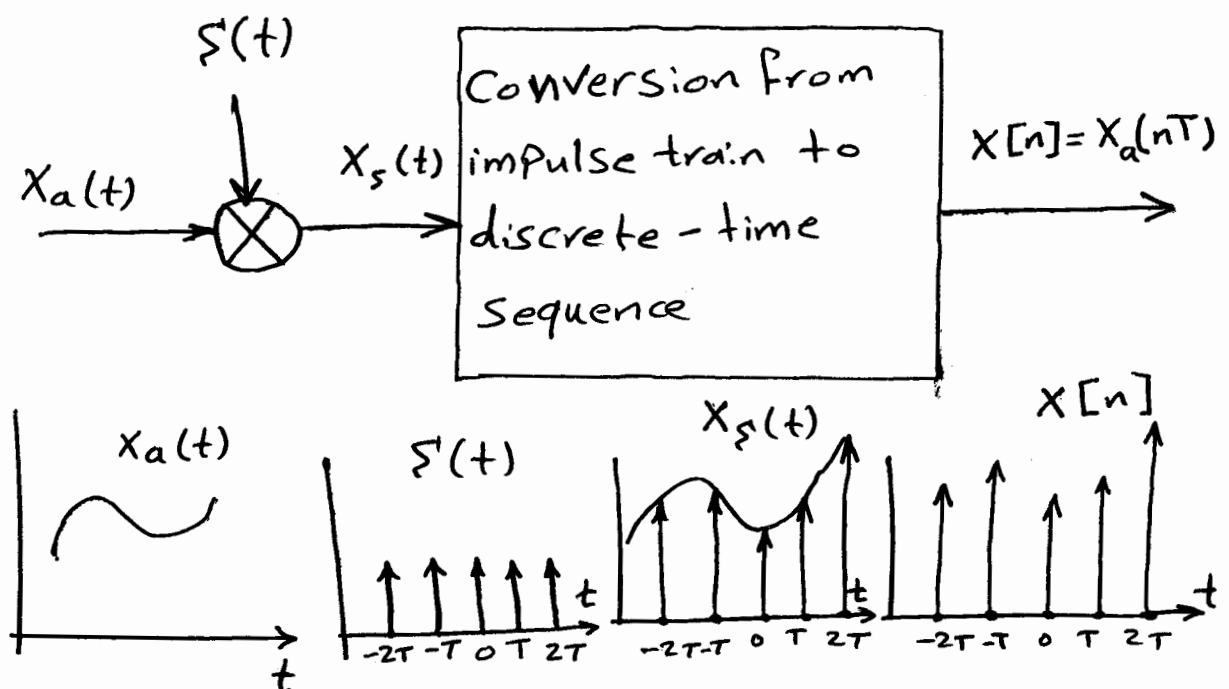
$$\omega_s = 2\pi f = \frac{2\pi}{T} \text{ rad/sec}$$



Continuous to Discrete time Converter
(C/D) converter

* in Practical setting the operation of Sampling is implemented by an analog-to-digital (A/D) converter. Important consideration in the implementation or choice of an A/D converter include quantization of the output samples, linearity of quantization steps and limitations on the sampling rate

* we use the following two stage mathematical representation of the sampling process



Frequency Domain Representation of Sampling

- * We are going to derive the frequency-domain relation between the input and output of an ideal C/D converter
- * Consider the relationship between $X_s(j\omega)$ and $X_a(j\omega)$
- * Consider the conversion of $X_a(t)$ to $X_s(t)$ through modulation of the periodic impulsive train

$$s(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$$

where $\delta(t)$ is the unit impulse function or (Dirac delta function)

- * We modulate $s(t)$ with $X_a(t)$ obtaining

$$\begin{aligned} X_s(t) &= X_a(t) s(t) = X_a(t) \sum_{n=-\infty}^{\infty} \delta(t - nT) \\ &= \sum_{n=-\infty}^{\infty} X_a(nT) \delta(t - nT) \end{aligned}$$

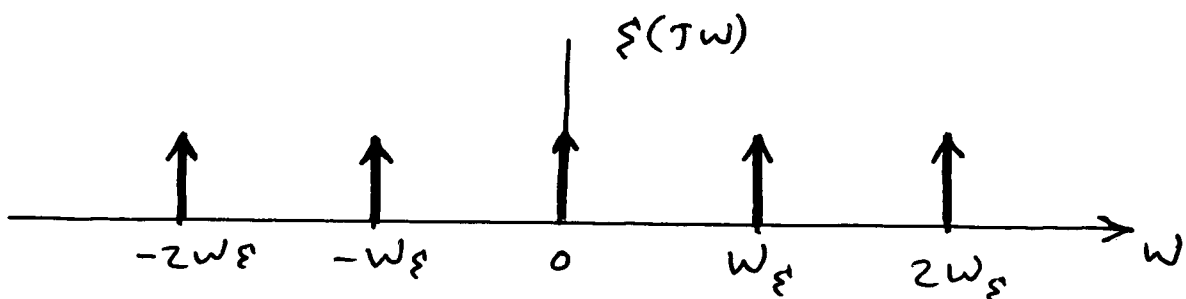
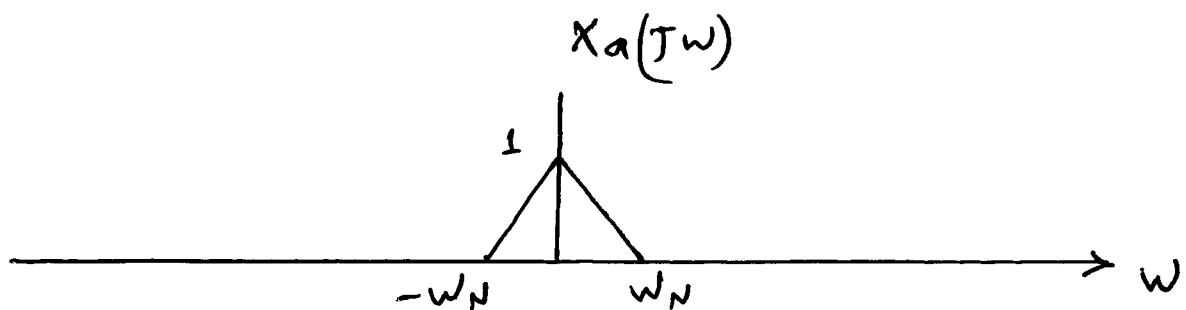
* The Fourier transform of a periodic impulse train is a periodic impulse train

$$\mathcal{F}(T\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_s)$$

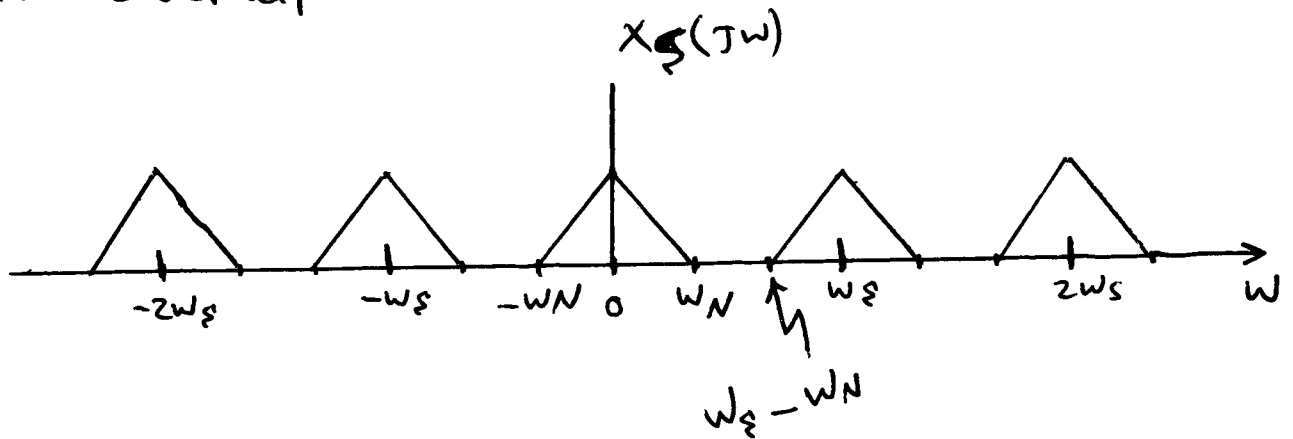
where

$$\omega_s = \frac{2\pi}{T}$$

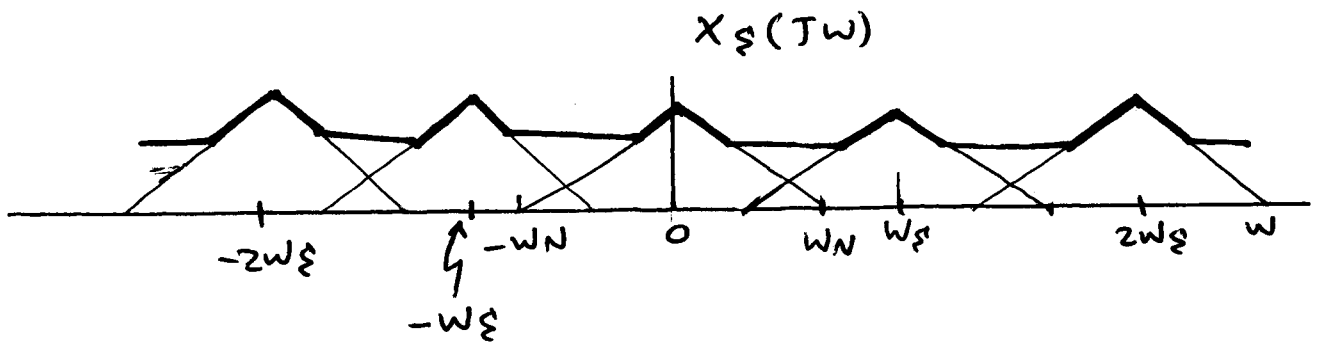
$$\begin{aligned} X_s(T\omega) &= \frac{1}{2\pi} X_a(T\omega) * \mathcal{F}(T\omega) \\ &= \frac{1}{T} \sum_{k=-\infty}^{\infty} X_a(T(\omega - k\omega_s)) \end{aligned}$$



* if $\omega_s > 2\omega_N$ the replicas of $x_a(j\omega)$ do not overlap



* if $\omega_s < 2\omega_N$, the replicas of $x_a(j\omega)$ is no longer recoverable



* The frequency ω_N is commonly referred as the Nyquist frequency

* The frequency $2\omega_N$ that must be exceeded by the sampling frequency is called the Nyquist rate